# Ensemble Spread as a Precursor for Extreme Space Weather Events



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### Data Assimilation for Data-Derived Models

#### Motivation

- Data assimilation is a powerful tool used to improve forecasts of nonlinear systems
- Data assimilation produces more accurate initial conditions by combining estimates from previous model forecasts and observations
- Ensemble techniques provide an efficient way to estimate model error by sampling nearby trajectories

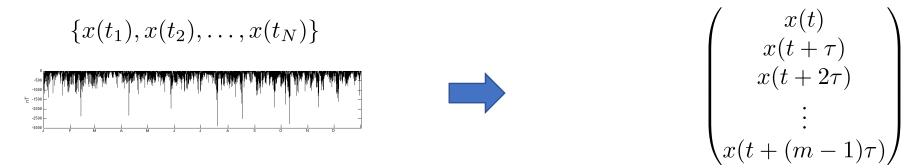
#### Goal:

- We apply the Ensemble Transform Kalman Filter (ETKF) to a data-derived model to produce better forecasts
- The spread of the forecast ensembles gives information about instability and can be used to forecast extreme events

# Phase space model constructed from a time series of scalar observations

Time Delay Vectors create multivariate phase space vectors from scalar time series

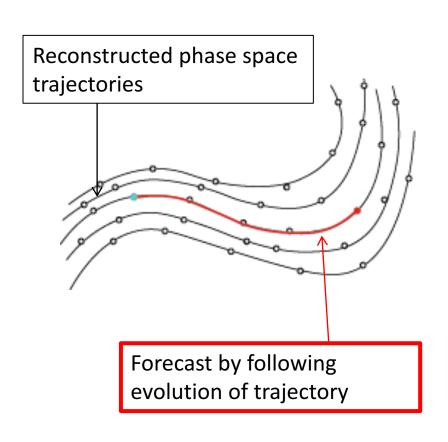
- Preserves features of the attractor
- Parameters to tune: time delay and dimension



#### Singular Spectrum Analysis reduces the dimension of the phase space

- Identify modes of variability
- Keep modes that represent most of the signal variance
- Reject those that correspond to noise

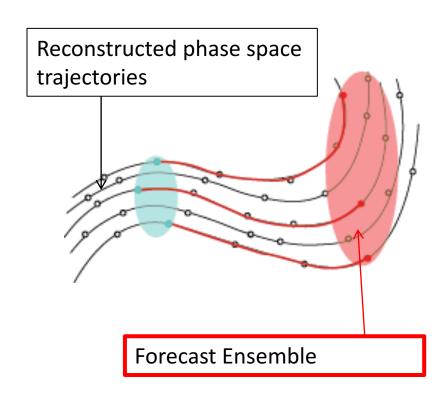
# Forecasts using a reconstructed phase space model



 Forecasts are made by following the reconstructed phase space trajectories

 Ensemble of forecasts made from slightly perturbed initial conditions

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# Ensemble Transform Kalman Filter (ETKF) with a Data-Derived Model

#### "Model" Forecast

Use a dense data set of points on the attractor (model) to advance NN analysis ensemble to the end of the analysis window

#### Nearest Neighbors (NN)

Locate nearest neighbors of analysis ensemble members to serve as analogs to make forecasts

#### **Observations**

Observations of a single variable (i.e. the AL index) become multivariate when embedded

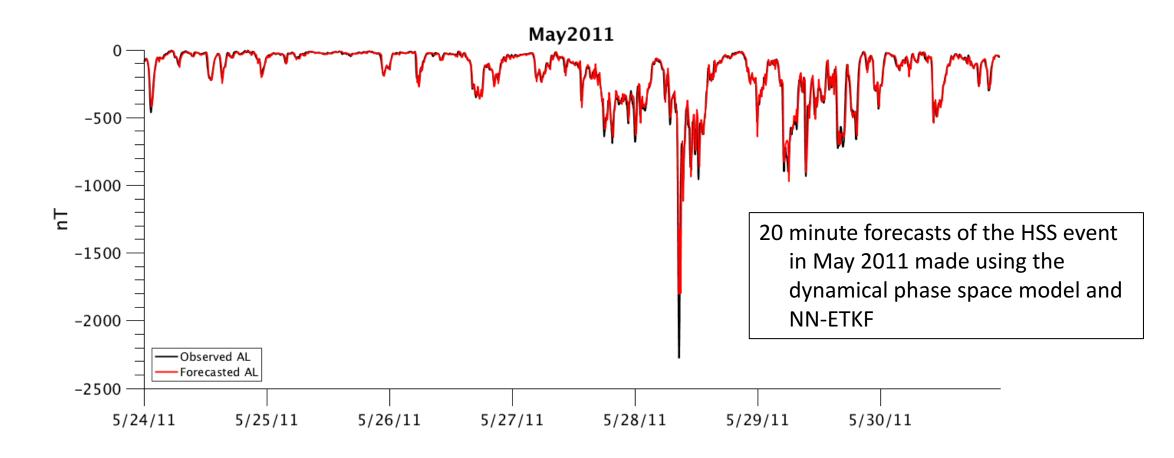
#### **Analysis**

Analysis ensemble members computed using the ETKF are the best estimates of the true state, but do not lie on the attractor

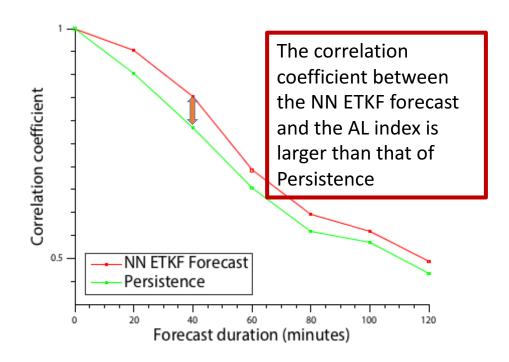


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# Forecast results using ETKF and date-derived model



### Forecasts improved by ETKF



#### **Skill Score**

$$SS = 1 - \frac{MSE_{\text{NN-ETKF}}}{MSE_{\text{Persistence}}}$$

For 20 minute forecasts

$$SS = 0.58$$

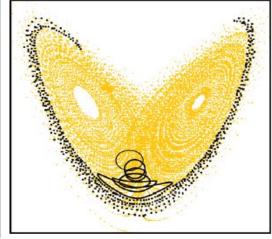
Positive skill scores implies NN-ETKF forecast is performing better than persistence

# Ensemble spread as a precursor to extreme events

 Consider the transition from one wing of Lorenz attractor to the other an extreme event



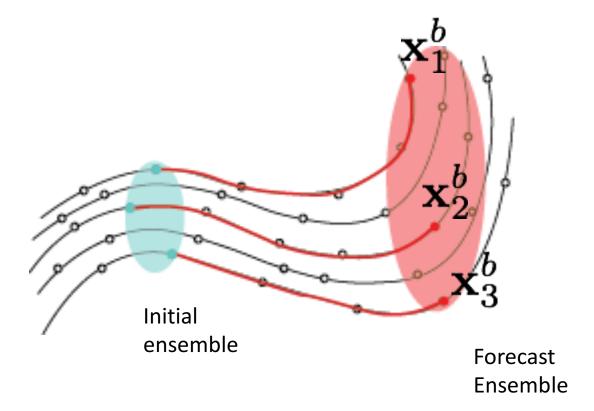




Non-extreme event

Extreme event

### **Ensemble Spread**



#### Forecast Ensemble

$$\mathbf{X}^b = \{\mathbf{x}_1^b, \dots, \mathbf{x}_M^b\}$$

Ensemble mean

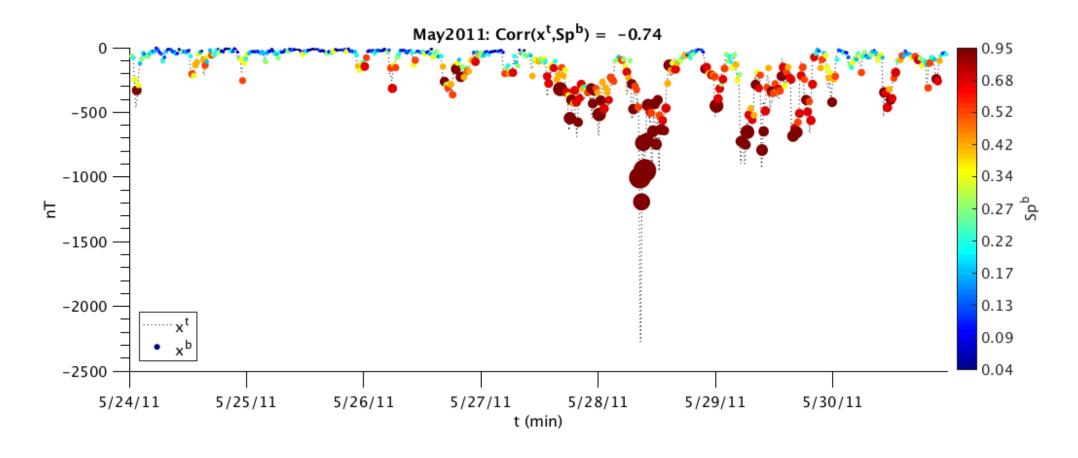
$$\bar{\mathbf{x}}^b = M^{-1} \sum_{i=1}^M \mathbf{x}_i^b$$

Ensemble spread

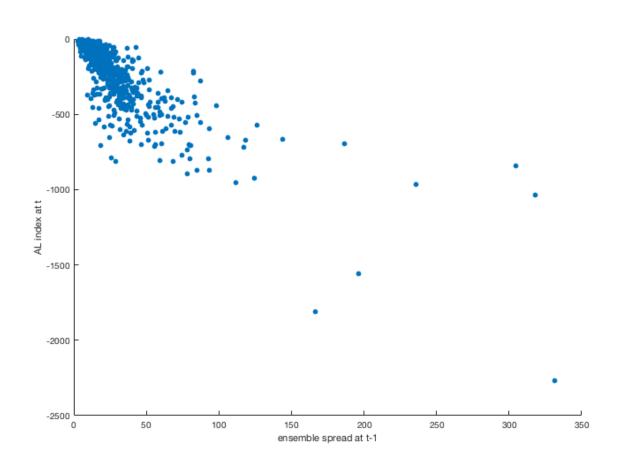
$$\hat{\mathbf{X}}^b = \{\mathbf{x}_1^b - \bar{\mathbf{x}}^b, \dots, \mathbf{x}_M^b - \bar{\mathbf{x}}^b\}$$
 $\mathbf{P}^b = (M-1)^{-1}\hat{\mathbf{X}}^b(\hat{\mathbf{X}}^b)^T$ 

$$= (M-1)^{b} \mathbf{A}^{b} \mathbf{A}^{b}$$
  $\operatorname{Sp}^{b} = \sqrt{\operatorname{Tr}(\mathbf{P}^{b})}$ 

# Ensemble Spread Correlates with the Magnitude of AL



### Ensemble spread time lagged correlation with the value of the AL index

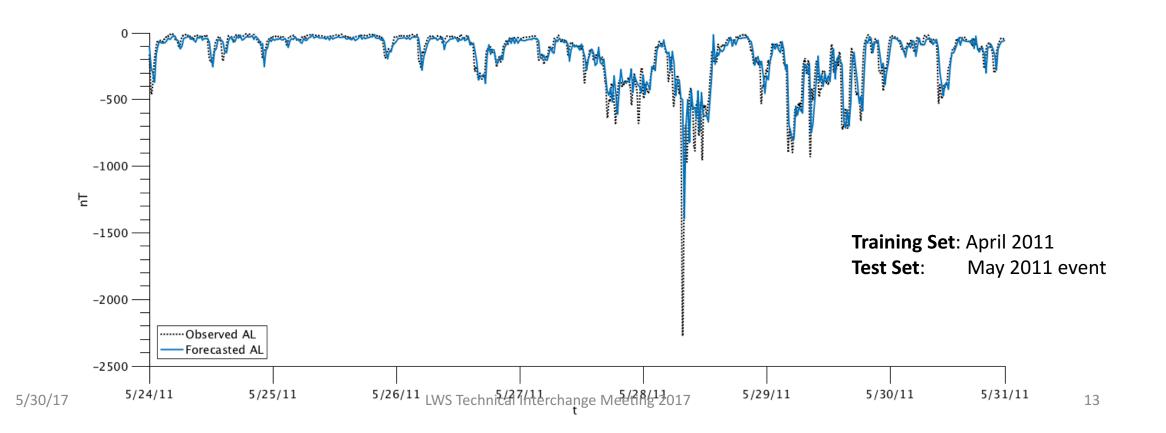


- The correlation between the spread of a forecast and the value of the AL index 20 minutes later is high
- Indicating that the spread of the previous forecast is a good predictor of the future value of the AL index

### Ensemble spread to forecast $\{x^b, x^p, S^b, \frac{dS^o}{dt}\}$

$$\{x^b, x^p, S^b, \frac{dS^b}{dt}\}$$

$$AL(t+1) = b_0 + b_1\bar{x}^b(t) + b_2AL(t-1) + b_3S^b(t) + b_4S^b(t-1)$$



### Summary

 We have successfully applied data assimilation to a data-derived model to produce

Ensemble forecasts using the ETKF improve predictions of the AL index

• We are able to identify the ensemble spread as an indicator of extreme events and can use as a precursor to predict their onset